Short Communication

Apparent negative values of Young’s moduli of lattice materials under dynamic conditions

S. Adhikari\textsuperscript{a,1}, T. Mukhopadhyay\textsuperscript{b,1,}\textsuperscript{*}, A. Shaw\textsuperscript{a}, N.P. Lavery\textsuperscript{a}

\textsuperscript{a}College of Engineering, Swansea University, Swansea, UK
\textsuperscript{b}Department of Aerospace Engineering, Indian Institute of Technology Kanpur, Kanpur, India

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\textbf{A B S T R A C T}

Lattice materials are characterised by their equivalent elastic moduli for analysing mechanical properties of the microstructures. The values of the elastic moduli under static forcing condition are primarily dependent on the geometric properties of the constituent unit cell and the mechanical properties of the intrinsic material. Under a static forcing condition, the equivalent elastic moduli (such as Young’s modulus) are always positive. When dynamic forcing is considered, the equivalent elastic moduli become functions of the applied frequency and they can be negative at certain frequency values. This paper, for the first time, explicitly demonstrates the occurrence of negative equivalent Young’s modulus in lattice materials experimentally. Using additively manufactured titanium-alloy lattice metastructures, it is shown that the real part of experimentally measured in-plane Young’s modulus becomes negative under a dynamic environment. In fact, we show that the onset of such negative Young’s modulus in lattice materials can be precisely determined by capturing the sub-wavelength scale dynamics of the system. Experimental confirmation of the negative Young’s moduli and the onset of the same as a function of frequency provide the necessary physical insights and confidence for its potential exploitation in various multi-functional structural systems and devices across different length scales.

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1. Introduction

Lattice materials are a particular type of mechanical metamaterials, typically characterised by the periodicity of a unit cell. A crucial aspect of metamaterials is that the overall property is largely dependent on the geometric features of the periodic unit cells besides the intrinsic property of the constituent material. Intense research in recent years show truly exciting developments such as ultralight metamaterials (Zheng et al., 2014) approaching theoretical strength limit (Berger, Wadley, & McMeeking, 2017), promise of exploiting stiffness most optimally and programmable shape modulation (Mukhopadhyay et al., 2020), pentamode materials (Kadic, Buckmann, Stenger, Thiel, & Wegener, 2012) with cloaking mode (Buckmann, Thiel, Kadic, Schittry, & Wegener, 2014), negative refraction elastic waves (Zhu, Liu, Hu, Sun, & Huang, 2014), elastic cloaking (Milton, Briane, & Willis, 2006; Stenger, Wilhelm, & Wegener, 2012), hyperbolic elastic metamaterials (García-Chocano, Christensen, & Sánchez-Dehesa, 2014), negative Poisson’s ratio (auxetic) materials (Lakes, 1987), materials with negative effective elastic modulus (Fang et al., 2006) and negative mass density (Yang, Mei, Yang, Chan, & Sheng, 2008).

\textsuperscript{1} Corresponding author.
\textsuperscript{*} E-mail address: tanmoy@iitk.ac.in (T. Mukhopadhyay).
\textsuperscript{1} First two authors as joint first authors.

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The interest in the current investigation is in the sub-acoustic range, which is typically considered to be below kHz range. In particular, this paper experimentally demonstrates the possibility of negative effective elastic moduli in 2D lattice metamaterials, and thereby investigates the onset of such negative Young’s modulus as a function of frequency.

Lattice-like forms are available in abundance in naturally occurring as well as artificial materials and structures across different length-scales (Chandra, Mukhopadhay, Adhikari, & Figiel, 2020; Gibson & Ashby, 1999; Gupta, Mukhopadhay, Roy, & Dey, 2020; Mahata & Mukhopadhay, 2018; Mukhopadhay & Adhikari, 2016c; 2017a). Methods to obtain effective properties (also know as homogenisation methods) of periodic elastic materials can be traced back to the classical work by Hashin and Shtrikman (1963). Exploiting periodic boundary conditions and mechanics of a unit cell, closed-form analytical expressions for equivalent elastic moduli for planar 2D cellular materials have been derived in Gibson and Ashby (1999), El-Sayed, Jones, and Burgess (1979), Mukhopadhay, Mahata, Zaeem, and Adhikari (2017b), Mukhopadhay, Mahata, Adhikari, and Zaeem (2017a), Mukhopadhay, Mahata, Adhikari, and Asle Zaeem (2018). Homogenisation of metamaterials with sub-wavelength dynamics needs to differ from the classical homogenisation approaches due to the fact that there are local resonators embedded in metamaterials. This has led to the development of dynamic homogenisation approaches (Craster, Kaplunov, & Pichugin, 2010; Nemat-Nasser, Willis, Srivastava, & Amir khizi, 2011; Norris, Shuvalov, & Kutsenko, 2012; Willis, 2009). The dynamic homogenisation can be viewed as a higher-order method (Srivastava, 2015) compared to the classical static homogenisation approaches. These homogenisation approaches are not strictly applicable when the unit cells are not periodic, as will be the case when random inhomogeneities are present in the metamaterial. To address this issue, the idea of ‘representative unit cell element (RUCE)’ was introduced in Mukhopadhay and Adhikari (2016b, 2017b) in the context of static homogenisation of cellular metamaterials. This approach is a step-change as it provides the geometric basis for considering inhomogeneities in cellular metamaterials and provides closed-form analytical expressions for equivalent (static) elastic properties. Homogenisation of continuum systems with random circular inclusions have been discussed recently (Pivovarov & Steinmann, 2016a; 2016b) for static problems.

Wave propagation in periodic structures (Brillouin, 1953) plays a crucial role in the analysis and design of metamaterials. Extensive works have been undertaken since the mid60’s on dynamics of periodic structures (Mead, 1996) in aerospace engineering. The main motivation was to efficiently analyse large aerospace structures made of periodic units (e.g., periodically stiffened shell in an aircraft fuselage). Current computational methods for metamaterials (Hussein, Leamy, & Ruzzene, 2014) rely on the Floquet–Bloch theorem for wave propagation, which in turn is based on periodic boundary condition for a unit cell. Overall wave propagation behaviour depends on the dynamic characteristics of a unit cell and can be understood in terms of the band-gaps (Brillouin, 1953; Deymier, 2013). Consequently, efficient analytical methods (Bigoni, Guenneau, Movchan, & Brun, 2013) and numerical methods for the computation of bandgaps of metamaterials have taken centre stage in most current research (Hussein, 2009a; Palermo & Marzani, 2016; Sugino, Leadenham, Ruzzene, & Erturk, 2016). Classical wave propagation approaches were developed for undamped metamaterials. Few authors have considered damped metamaterials (Hussein, 2009b) where internal damping within a unit cell is considered explicitly (Hussein & Frazier, 2013; Yu et al., 2017). Bandgaps analysis for damped metamaterials needs the solution of a complex eigenvalue problem, which poses a computational challenge (Phani & Hussein, 2013). The dynamic behaviour of periodic structures can change drastically due to the presence of disorders (Hodges, 1982). Experimental works (Hodges & Woodhouse, 1983) show that in such cases a vibration can localise (Pierre & Cha, 1989), similar to the phenomenon of Anderson’s localisation (Anderson, 1958) in atomic crystals.

Static elastic moduli of metamaterials differ from the elastic moduli under a vibrating condition (Mukhopadhay, Adhikari, & Alu, 2019a). Such dynamic elastic moduli are a function of the forcing frequency of vibration. The difference is due to the fact that deformation behaviour of the constituting members (such as the beam indicated in Fig. 1(c)) is different in static and dynamic environments. This essentially leads to the significant deviation in elastic moduli of lattice materials, which is actually a network of such constituent members. The enhanced elastic moduli has been proposed to be exploited in the optimum design of various structural systems (such as aircraft wings and turbine blades), which are subjected to vibration during the operational condition (Mukhopadhay et al., 2019a). It can be shown that the elastic moduli could become negative at certain frequencies depending on the microstructural configuration. In a recent paper, the sub-wavelength scale dynamics in the deformation of a constituent beam element has been captured based on dynamic stiffness approach. This has led to the derivation of closed-form analytical limits of negative elastic moduli (Mukhopadhay, Adhikari, & Alu, 2019b).

Negative Youngs moduli under a dynamic condition are directly relevant to developing tunable metamaterials for acoustic wave propagation (Hou & Assouar, 2015). This will lead to modulation of phase including complete inversion (π/2 switch) during wave propagation. Such an unusual behaviour in lattice materials potentially result in interesting applications such as acoustic cloak for waves, acoustic negative refraction, noise elimination and vibration reduction. The exploitation of this phenomenon can be utilized in a wide range of mechanical and acoustic systems where the modulation of dynamic properties are necessary. Another significant aspect arising from negative Youngs moduli is the low-frequency phase transformation and modulation. This makes the incredible possibility of practical applications at the sub-acoustic range such as at mechanical frequencies and even in seismic frequency ranges. Exploiting phase shifts and reversals, one can develop low-frequency adaptive programmable materials with applications in future aircraft, automotive, smart buildings and micro-mechanical devices and systems.

The possibility of effective negative elastic moduli in lattice materials has been explored mostly via theoretical approaches. Till date, little/no experimental evidences have been put forward in the sub-acoustic range. This paper endeavours
to outline the experimental methods and results aimed at understanding effective negative in-plane elastic moduli of 2D hexagonal lattices and the onset of such negative values. We have fabricated a hexagonal lattice made of a Titanium alloy with dimension $215 \times 115 \times 15$ mm$^3$ for this purpose. We consider a frequency range of $0 - 3000$ Hz to obtain the effective in-plane elastic moduli of the lattice sample. Outline of the paper is as follows: theoretical background behind negative Young’s moduli for cellular materials is discussed in Section 2; Section 3 covers the manufacturing of the honeycomb, the testing setup and main results arising from the experimental investigation; finally, a brief summary and concluding remarks on this work are presented in Section 4.

2. Theoretical background for negative Young’s moduli

It is common practice to model lattice microstructures as continuous solid medium, wherein a unit cell based approach can be adopted to obtain the effective elastic moduli for the entire solid domain (Gibson & Ashby, 1999; Khakalo, Balobanov, & Niiranen, 2018; Mukhopadhyay & Adhikari, 2016a; Mukhopadhyay, Adhikari, & Batou, 2019c; Zhang, Wang, & Kang, 2019). It has been shown theoretically that lattice materials with hexagonal honeycomb-like structures can exhibit negative Young’s
modulus under a dynamic environment (Mukhopadhyay et al., 2019b). The frequency corresponding to the onset of such negative Young’s modulus in a honeycomb-like lattice material can be obtained based on dynamic stiffness approach in a multi-scale framework (Mukhopadhyay et al., 2019b)

\[ \omega_{E1,E2}^* \approx \frac{5.598}{m} \frac{EI}{l^2} \]

where \( m, E \) and \( l \) are the mass per unit length, intrinsic Young’s modulus and area moment of inertia of the beam elements shown in Fig. 1(c), respectively, while the geometric dimension \( l \) is indicated in the same figure. Here \( \omega_{E1,E2}^* \) denotes the fundamental inflection frequency, where the Young’s moduli (both \( E_1 \) and \( E_2 \)) change sign from positive to negative. For a lightly damped microstructure, the equivalent Young’s moduli will become negative for the first time beyond this frequency value. In other words, the above expression provides the lowest value of frequency to achieve negative Young’s modulus. This will lead to a situation where the direction of steady-state dynamic response will be opposite to the forcing direction.

In the current paper we endeavour to undertake an experimental realization of the onset of negative Young’s moduli. It can be noted that the inflection frequency is same for both longitudinal and transverse Young’s moduli (\( E_1 \) and \( E_2 \)) and it only depends on the geometric parameter \( l \) along with the intrinsic material properties. Thus this inflection frequency is invariant to the non-auxetic (refer to Fig. 1(d)) or auxetic (refer to Fig. 1(e)) nature of the lattice geometry. The specimens of hexagonal honeycombs for carrying out experimental investigation are prepared using additive manufacturing with Titanium alloy Ti-6Al-4V as intrinsic material. It can be noticed in Fig. 1(d - e) that the specimens are manufactured with additional solid metallic tabs at both ends for experimental convenience. However, these metallic tabs would influence the dynamic properties of the hexagonal lattice structures leading to erroneous experimental results. In the analytical expression for inflection frequency (refer to Eq. (1)) the effect of such additional metallic tab has not been included. Thus to compare the analytical predictions with experimental results, it is necessary to include the influence of this metallic tab. Here we derive an analytical framework to take into account the error caused by the additional component attached to the honeycomb lattice.

An equivalent continuum representation of the specimen is shown in Fig. 1(f), where the middle portion of length \( L_2 \) has a lattice microstructure with equivalent Young’s modulus \( E’ \) and the two tabs of length \( L_1 \) each have Young’s modulus \( E” \). For the purpose of the current derivation of inflection frequency, we concentrate on the Young’s modulus in direction-2 according to Fig. 1, which is essentially the in-plane direction perpendicular to the dimensions \( L_1 \) and \( L_2 \) in Fig. 1(f). Under a dynamic environment, the equivalent Young’s modulus \( E” \) of a honeycomb lattice is given by (Mukhopadhyay et al., 2019b)

\[ E”(\omega) = \frac{D_{33}(h + l \sin \theta)}{lb \cos^3 \theta} \]

Here \( b \) is the thickness of honeycomb sheet as indicated in Fig. 1(f). \( D_{33} \) is a component of the dynamic stiffness matrix for a beam element (Mukhopadhyay et al., 2019b)

\[ D_{33} = \frac{-Ebl^3(cS + Cs)}{(cc - 1)} \]

where \( c = \cosh(bL), \quad c = \cos(bL), \quad S = \sinh(bL), \quad s = \sin(bL). \) \( D_{33} \) is a frequency dependent complex quantity because \( b \) is a function of \( \omega \) and the damping factors (Mukhopadhyay et al., 2019b). The equivalent Young’s modulus of the solid metallic tabs at the two ends of the lattice structure under dynamic environment is given by (Leung, 1993)

\[ E” = E’\psi \cot \psi \]

where \( \psi^2 = \frac{\omega^2 \rho L^2}{E} \) and \( \rho \) is the density of intrinsic material such that \( m = \rho \times \) [area of the connecting beam elements]. It can be noted here that the intrinsic Young’s modulus of the lattice part in Fig. 1(f) and the Young’s modulus of the solid metallic tabs are denoted by \( E \) (both the parts are manufactured using same material).

If an in-plane force is applied along the two edges of the length \( L (= 2L_1 + L_2) \) in direction-2 (i.e. perpendicular to the dimensions \( L_1 \) and \( L_2 \)), the components of the forces shared by the honeycomb part of length \( L_2 \) and the metallic tabs of length \( L_1 \) each would be according to their respective axial stiffness.

\[ \frac{LbE_{eq}}{L'} = \frac{2L_1\bar{b}E’}{L'} + \frac{L_2\bar{b}E’}{L'} \]

where \( E_{eq} \) is the equivalent Young’s modulus of the entire structure including the metallic tabs. From the above equation, the expression of \( E_{eq} \) can be written as

\[ E_{eq} = \frac{E_1L_2}{L} + 2E”\frac{L_1}{L} \]

Substituting \( E’ \) and \( E” \), the above expression can be modified as

\[ E_{eq} = D_{33}A + E’\psi \cot \psi B \]
where \( A = \frac{(h + l \sin \theta) L_2}{(h b \cos^2 \theta) L} \) and \( B = \frac{2 L_1}{L} \). Expanding the expression of \( D_{33} \) (by a Taylor series in the frequency parameter \( \omega \); refer to Eq. (3)) and cot \( \psi \), the above equation becomes

\[
E_{eq}(\omega) = \left[ 12 \frac{EI}{L^3} - \frac{13}{35} m l \omega^2 - \frac{59}{161700} \frac{l^5 m^2 \omega^4}{EI} + \cdots \right] A
+ \left[ \pm \omega^2 \sqrt{\frac{l}{E}} \left( \frac{1}{\pm \omega l' \sqrt{\frac{EI}{l}}} - \frac{1}{3} \left( \pm \omega l' \sqrt{\frac{EI}{l}} \right)^2 - \frac{1}{45} \left( \pm \omega l' \sqrt{\frac{EI}{l}} \right)^3 + \cdots \right) \right] B
\]

The value of \( \omega \) for which \( E_{eq} \) becomes zero can be obtained by solving \( E_{eq} = 0 \), where retaining up to fourth order terms of \( \omega \) (refer to Eq. (8))

\[
\left( \frac{59}{161700} \frac{l^5 m^2}{EI} \right) \omega^4 + \left( \frac{13 m l}{35} + \frac{E l^2 \rho B}{3E A} \right) \omega^2 - \left( \frac{12E l}{l^3} + E \frac{B}{A} \right) = 0
\]

The solution of Eq. (9) gives the frequency in the vicinity of \( \omega = 0 \), where the Young’s modulus changes sign from positive to negative.

As a special case of the above derivation, when no metallic tab is present at the two ends (i.e. \( L_1 = 0 \) and \( L_2 = L \)), the parameter \( B \) becomes 0. Subsequently, Eq. (9) reduces to

\[
\left( \frac{59}{161700} \frac{l^5 m^2}{EI} \right) \omega^4 + \frac{13 m l}{35} \omega^2 - \frac{12E l}{l^3} = 0
\]

Solution of the above expression exactly matches with Eq. (1). This observation essentially corroborates to further confidence in the current theoretical development. It is worthy to keep in mind at the current stage that Eq. (9) can obtain fundamental inflection frequency including the effect of error induced due the presence of the two metallic tabs, which are designed essentially for operational convenience in the experimental setup. The current theoretical development of Eq. (9) is solely to facilitate a comparison with the experimental outcome. The analytical framework presented in this section is valid for low cell wall thickness of the lattice structure. The in-plane dimensions of the experimental specimen are indicated in Fig. 2(b), while thickness in the out-of-plane direction is 0.015m. The intrinsic material properties of Titanium alloy Ti-6Al-4V are considered as: \( E = 110 \text{ GPa} \) and \( \rho = 4.7 \times 10^3 \text{ kg/m}^3 \). Using Eq. (9), the fundamental inflection frequency is obtained as (discarding the negative and imaginary results for \( \omega \) ) \( \omega = 1177 \text{ Hz} \). In the following section, we will verify this value experimentally.

3. Experimental investigation for the negative Young’s moduli

3.1. Additive manufacturing of the honeycomb

The Ti-6Al-4V lattice materials were additively manufactured on a Renishaw RenAM 500 M, which is a Laser Powder Bed Fusion (L-PBF) process. The RenAM 500 M system uses a 500 W Ytterbium fibre laser to melt Ti-6Al-4V gas atomised powder onto a 250 mm \( \times \) 250 mm build plate, on a layer by layer basis, up to a maximum built height of 280 mm. In this instance the Ti-6Al-4V powder was ELI grade and supplied by LPW. The parameters used in these builds were a power of 400W, a layer thickness of 60 \( \mu \)m, a point distance of 80 \( \mu \)m, an exposure time of 60 \( \mu \)s, and a hatch spacing of 100 \( \mu \)m. Both the non-auxetic lattice in Fig. 1(d) and the auxetic lattice in Fig. 1(e) were built directly onto the base plate without any support structure, but with an additional 1mm sacrificial layer. The lattices were then removed from the base plate using Electric Discharge Machining (EDM) so that the thickness \( b \) in Fig. 1(f) was 15 mm. The final dimension of the lattices in XY plane come to 215 mm \( \times \) 115 mm. Residual stress is known to affect mechanical properties, however, no stress relieving post-build heat treatments were used in this instance, which resulted in a small spring-back deformation in the build direction after removal from the plate. Both machine parameters (Sillars et al., 2018) and heat treatments (Lavery et al., 2017) can be used in combination to reduce residual stress levels in the material and hence reduced distortion on removal from the base plate. Furthermore, it is also known that there will be a small amount of porosity (< 0.1%) which will also affect both elastic and plastic properties of the material, and this could be reduced using hot isostatic pressing (Lavery et al., 2017).

3.2. Testing setup

The additively manufactured honeycomb structure is tested using an impact hammer. This is achieved with the aid of DataPhysics software and the 901 Series dynamic signal analyser to return the Frequency Response Functions (FRFs) between the force sensor in the hammer tip and the accelerometers. After some initial testings, a frequency bandwidth of 6400Hz is used for the sample. Due to the higher natural frequencies, a stiff tip is used on the hammer in order to create a shorter pulse duration and increase the frequency range generated, and an exponential window was used to ameliorate the potential problem of leakage and improve the signal to noise ratio by reducing the influence of the noise long after the impact (Ewins, 2000).
Boundary conditions for the experiment are a major consideration. Incorrect mounting of the structure for testing can dramatically change the results of the testing. In experimental analysis completely free boundary conditions can never be replicated; however, soft mounts were used to approximate free-free conditions. Hanging the structures so that the plane of the structure is vertical and suspended by elastic threads connected to each of the top corners ensures maximum freedom of movement for the structure during testing.

For the purpose of cross checking signals and to assist in verifying that the vibration is fundamentally axial in nature, four accelerometers are attached to the structure. One accelerometer is placed at each edge as displayed in Fig. 2(a). These measure the acceleration of the structures in g, when subject to impact from the hammer. Placement of these accelerometers on the structures are also considered. If they were placed too close to a node of a mode shape, that particular accelerometer could be a potential noise source, as it would experience low amplitudes. Here effect of the small additional mass caused by the physical attachment of sensors to the structure is neglected.
To obtain the in-plane axial response, the impact of the hammer is applied to the top of the honeycomb structure, as centrally as can be practically achieved. Using the accelerometers, accelerance (acceleration per unit force) frequency response functions (FRF) are produced. These are evaluated, determining the response to excitation vibration and thus the modal response at resonance. In total five channels of data have been stored. They include four accelerometers shown in Fig. 2(a) and the impact hammer. The real and imaginary parts of the frequency response for all the five channels have been stored for all the frequency points. The relative deformation of the lattice is obtained by subtracting the accelerometer reading of the opposite edges and dividing the resulting complex vector by frequency-square (note $A = -\omega^2 X$, where $A$ is the acceleration and $X$ is the displacement). The effective dynamic strain is therefore obtained by dividing this quantity by the overall length of the lattice. The measured frequency dependent force is divided by the surface area of the top of the lattice to obtain the applied stress. The ratio of the effective stress and stain calculated this way gives the measured Young’s modulus and is plotted in Fig. 2(c) by separating the real and imaginary parts.

3.3. Results

Experimental results for the real and imaginary parts of the frequency-dependent Young’s modulus in direction 2 is plotted as a function of frequency in Fig. 2(c). We show in this figure experimentally that negative Young’s modulus can be achieved in a dynamic environment. From the figure it can be noticed that real part of the Young’s modulus changes sign from positive to negative at a frequency of 1161 Hz, which is the onset of negative Young’s modulus. It is interesting to note that the value is close to the theoretical prediction (1177 Hz) using Eq. (9), as presented in the preceding section. This equation has been developed by incorporating the effect of two metallic tabs which are attached to the honeycomb panel for experimental convenience. In other words, since the prediction of Eq. (1) is not directly comparable to the current experimental outcomes, the Eq. (1) is modified further to incorporate the error induced by two additional metallic tabs. Close agreement between the modified theoretical framework and experimental outcomes essentially indicates the validity of Eq. (1), which can predict the onset of negative Young’s modulus without any influence of the metallic tabs. After obtaining enough confidence in the closed-form expression of fundamental inﬂection frequency (deﬁned by the frequency where the elastic modulus changes sign for the ﬁrst time (Mukhopadhyay et al., 2019b)) based on the current experimental results, we investigate the effect of different material and geometric parameters that inﬂuence the onset of negative Young’s modulus (both longitudinal and transverse). Fig. 2(d) shows the effect of two geometric parameters ($l$ and $I$) and two intrinsic material properties ($m$ and $E$) on the fundamental inﬂection frequency. For the purpose of carrying out this numerical investigation, we have taken a range [0.5X 1.5X] of the four parameters, where $X$ denotes the nominal value of the four parameters considered for carrying out the experiments. The abscissa of Fig. 2(d) is normalized with respect to the respective $X$ values of each parameter. From the ﬁgure it is evident that the fundamental inflection frequency reduces with the increase in $l$ and $m$, while the sensitivity of $l$ is signiﬁcantly higher compared to $m$. Both $E$ and $I$ can be noticed to have an opposite effect on the fundamental inﬂection frequency and their relative sensitivity is equal.

4. Conclusions

This paper presents an experimental investigation on the dynamic behaviour of lattice materials leading to the realization of the onset of negative Young’s moduli. Under a static forcing condition, the equivalent elastic moduli of a material are always positive, which has been the traditional understanding of material behaviour for decades. However, it has recently been shown that the negative equivalent elastic moduli of lattice materials can be attained under a dynamic environment at certain frequency values. This paper attempts for the first time to demonstrate the occurrence of negative equivalent Young’s modulus in lattice materials experimentally, and thereby identify the onset of such negative Young’s modulus. Using hexagonal honeycomb lattices made of titanium alloy, it is shown that the real part of in-plane Young’s modulus becomes negative under a dynamic environment. We have established that the onset of such negative Young’s modulus in lattice materials can be precisely determined by capturing the sub-wavelength scale dynamics based on a modiﬁed analytical formulation including the effect of experimental setup. Thus the paper presents a comprehensive argument using both experimental investigation and a strong theoretical framework. The onset of negative Young’s modulus is found to depend on certain material and geometric parameters of the lattice microstructure in a unique manner, which is numerically characterised as an integral part of this investigation. Although we have concentrated on hexagonal lattices in this paper, the experimental approach is generic in nature and could be extended to other lattices in two and three dimensions. In essence, the investigation presented in this article to identify the onset of negative Young’s modulus in lattice materials would signiﬁcantly contribute to the development of futuristic material microstructures at multiple length scales for exploiting the new dimensions of elastic moduli unravelled in the dynamic regime.

Declaration of Competing Interest

The authors declare that they have no known competing ﬁnancial interests or personal relationships that could have appeared to inﬂuence the work reported in this paper.
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